

# Aspects of voyage planning on a small tonnage Finnish flag general cargo vessel

Kristo Kööp

Degree Thesis Bachelor of Maritime Management Degree Programme in Maritime Management, Captain Turku 2023

#### **DEGREE THESIS**

Author: Kristo Kööp

Degree Programme and place of study: Maritime Management, Novia

Specialisation: Bachelor of Maritime Management

Supervisor(s): Peter Björkroth, Ritva Lindell, Tony Karlsson

Title: Aspects of voyage planning on a small tonnage Finnish flag general cargo vessel

Date: 15.05.2023 Number of pages: 31 Appendices: 0

Abstract

The aim was to create a portfolio, that describes the steps taken into consideration on a small tonnage Finnish flag vessel when creating a voyage plan, and to create study guide for young officers on voyage planning. The author is a 2<sup>nd</sup> officer on a general cargo vessel under a Finnish flag, who is responsible for making voyage plans. The author must take into consideration the policies, international conventions and procedures in place when creating a passage plan for an upcoming voyage and follow the Company Specific quality guidelines.

This paper consists of an example voyage plan that was created for a real-life trip from Halmstad, Sweden to Wismar, Germany.

The author describes his steps when creating a voyage plan and what he has to take into consideration. The author discusses the advantages and disadvantages of having a standardized voyage planning guide.

This study can be used as a guide to students or ship personnel when creating a voyage plan.

Language: English

Key Words: voyage planning, bridge officer, safety of navigation

# **Table of Contents**

1	Intro	oduction	
2	Nav	rigation	1
	2.1.	1 Introduction	1
	2.1.	2 Instruments used on this vessel	1
3	Brid	lge team	1
	3.1.	1 Bridge manning	1
	3.1.	2 Bridge team's responsibilities	2
4	Intro	oduction to voyage planning	2
	4.1	Introduction	2
	4.2	Nautical Charts and Publications	3
	4.3	Voyage Plan Table	4
	4.4	Navigational Warnings	4
	4.5	Electronic Nautical Chart (ENC) accuracy	4
	4.6	Voyage Plan template	6
5	Voy	rage from Halmstad to Wismar	
	5.1	Introduction	
	5.2	Initial voyage plan	
	5.3	Detailed voyage plan	
6	Pre-	-departure briefing	
7	Dep	parture	
8	Ove	erlook of the produced voyage	
	8.1.	1 General overlook of the produced voyage	
	8.1.	2 Produced route in ECDIS	
	8.1.	3 Produced voyage plan	
9	Disc	cussion	

10	List of figures	. 31
	5	
11	Sources	. 31

# 1 Introduction

How we navigate our vessel safely and environmentally friendly is based on different policies, international conventions and ISO standards issued to the company. For the simplicity of this paper, I will be concentrating on the Voyage Plan Guidance from the Safety Management System (SMS) of the vessel.

# 2 Navigation

#### 2.1.1 Introduction

When planning a passage on our vessel, we follow the guidelines from the Voyage Plan Guidance from the SMS. One of the big factors taken into consideration with the passage plan is the safety of the vessel, human lives, and the cargo.

#### 2.1.2 Instruments used on this vessel

On our ship, we have 2 Transas 4000 ECDIS, 2 Furuno FAR radars, Anschutz gyro compass, Kelvin Hughes magnetic compass, Anschutz Pilotstar D autopilot, Furuno FE-700 echo sounder, Furuno GP-150 GPS, Navigator MK-10 GPS, Furuno MF HF DSC-6 terminal/receiver, Sailor 6222 VHF DSC, Furuno FM-8500 VHF and Sailor 6018 GMDSS Inmarsat C terminal.

# 3 Bridge team

# 3.1.1 Bridge manning

At sea, our bridge is manned by 1 licensed bridge officer and 1 lookout. The rotations are set out as following: 0000-0400 2nd officer and ordinary seaman (OS), 0400-0800 chief officer and OS, 0800-1200 master and ordinary seaman, 1200-1600 2nd officer and able seaman (AB), 1600-2000 chief officer and AB, 2000-0000 master and AB.

# **3.1.2** Bridge team's responsibilities

Master – overall command of the vessel, has the watches 0800-1200, 2000-0000.

Chief officer – in charge of ship's maintenance, cargo plans, medicals, security threats, onscene commander during firefighting, oil spills, boat crew during man overboard (MOB) situations. Has the watches 0400-0800, 1600-2000.

Second officer – in charge of voyage planning, chart, and publication updates, GMDSS equipment maintenance, safety officer, crew familiarization, training, lifesaving appliances and their maintenance, fire-fighting equipment maintenance and upkeep. Has the watches 0000-0400, 1200-1600.

The navigation at sea is done by all the officers, so it's important that the passage plan is done in such a way, that everyone involved can understand it and follow it.

# 4 Introduction to voyage planning

#### 4.1 Introduction

When planning routes on our ship, the author uses guidelines and templates provided by the company in the SMS. The Voyage Plan Guidance describes in detail what has to be taken into consideration when preparing a passage plan from point A to point B. A proper voyage plan must ensure a safe passage, safety of the vessel, human lives, cargo and the environment.

Before departure, a prepared voyage plan is checked by the master. The voyage plan has to cover the entire passage from berth to berth. It also includes the consumptions of technical liquids, speed, distances in Emission Control Areas (ECA), fuels, how much bunker, lube oil, fresh water we have on board. We must ensure that the voyage is not outside the legal and insured trading limits.

In addition, the depth calculations must be completed before departure. These include the latest information of displacement and draughts which are given to the second officer by

the chief officer and different allowances, such as squat effect, freshwater allowance, heel effect allowance, wave response allowance, company policy allowance, and chart inaccuracy (CATZOC) calculations. These calculations take into consideration open waters and restricted channels of width of 108,8 meters or less.

The master approves the settings for Safety Depth, Safety Contour, Warning Sector and Cross Track Error (XTE) before the voyage. Different settings may be applied to different legs of the voyage, which are also indicated in the Voyage Plan Table, if applicable.

Once we have departed to our voyage, the voyage plan is followed. If it is necessary to make any changes during the voyage, i.e due to weather, emergency, change in orders, the plan will be modified and approved by the master. If it is necessary to make any changes to avoid danger or to follow the Convention on the International Regulations for Preventing Collisions at Sea (COLREG), then the Officer of the Watch (OOW) shall make the changes and return the ship to the planned route after the danger has passed.

#### 4.2 Nautical Charts and Publications

As we don't use paper charts, the latest updates and subscriptions to charts must be ordered and installed to the ECDIS (Electronic Chart Display and Information System). This is done through Datema Chartplanner system. We also use digital nautical publications, which must be updated before departure through the Datema Digital Bookshelf system.

The charts and publications are updated every week to have the latest versions available. When ordering charts, we take into consideration possible deviations due to weather, so that we are still able to navigate safely regardless of where we have to deviate.

# 4.3 Voyage Plan Table

In our vessel, we use printed Voyage Plan Table supplemented with digital waypoint list.

A Voyage Plan Table must include:

- Reporting points
- Changes in ECDIS settings (if applicable)
- Speed limits (if applicable)
- Any other restrictions
- Essential navigational details
- Narrow and shallow passages

#### 4.4 Navigational Warnings

For manual updates, we use our INMARSAT system, which receives Enhanced Group Calling (EGC) messages with latest navigational and weather warnings. These messages are checked before and throughout the voyage.

### 4.5 Electronic Nautical Chart (ENC) accuracy

During the voyage planning process, we must assess the accuracy of ENC data. The zones of confidence (CATZOCs) provide the maximum errors per depth and position. This is one of the most important parts, as there are several parts of the sea which were mapped years ago and with different techniques used. Furthermore, when calculating the Minimum Safe Transit Depth (MSTD), safety contour and maximum transit speed, additional safety margins are applied for areas of low accuracy.

We also must take into consideration the time when the assigned CATZOC survey was carried out, and the effects of geological instability.

zoc	Position Accuracy	Depth Accura	icy	Seafloor Coverage	Typical Survey Characteristics	Symbol
A1	±5 m	= 0.50 + 1%d		Full area search undertaken. All	Controlled, systematic survey, high position	
		Depth (m)	Accuracy (m)	significant seafloor features detected and depths	and depth accuracy achieved using DGPS or a minimum three high	* * *
		10 30 100 1000	± 0.6 ± 0.8 ± 1.5 ± 10.5	measured.	quality lines of position (LOP) and a multibeam, channel or mechanical sweep system	* *
A2	± 20 m	= 1.00 + 2%d		Full area search undertaken, All	Controlled, systematic survey achieving	
		Depth (m)	Accuracy (m)	significant seafloor features detected and depths	position and depth accuracy less than ZOC A1 and using a modern	* * *
		10 30 100 1000	± 1.2 ± 1.6 ± 3.0 ± 21.0	measured.	survey echosouder and a sonar or mechanical sweep system	* *
в	± 50 m	= 1.00 + 2%d		Full area search not achieved: uncharted	Controlled, systematic survey achieving similar	
		Depth (m)	Accuracy (m)	features, hazardous to surface navigation are not expected	depth but lesser position accuracies than ZOC A2, using a	* * *
		10 30 100 1000	± 1.2 ± 1.6 ± 3.0 ± 21.0	but may exist	modern survey echosouder but no sonar or mechanical sweep system	* * *
с	± 500 m	= 2.00 + 5%d		Full area search not achieved, depth	Low accurancy survey or data collected on an	
		Depth (m)	Accuracy (m)	anomalies may be expected.	opportunity basis such as soundings on	
		10 30 100 1000	± 2.5 ± 3.5 ± 7.0 ± 52.0		passage	* * *
D	Worse than ZOC C	Worse than Zo	DC C	Full area search not achieved, large depth anomalies may be expected.	Poor quality data or data that cannot be quality assessed due to lack of information	* *
U	Unassesse	d – The quality	of the bathyme	tric data has yet to be as	ssessed	U

Figure 1. Zones of confidence, their accuracy, and symbols on ECDIS screen.

For example, if on ENC chart, CATZOC is a confidence zone A2 on planned route, it would mean that in that location of depths marked on this chart may be inaccurate by approximately 20 meters; or the possible error of the depth is 1 meter + 2% of the depth, e.g, if the mapped depth shows 10 meters, the error could be 1.2 meters (1 meter + 2% of 10 meters).

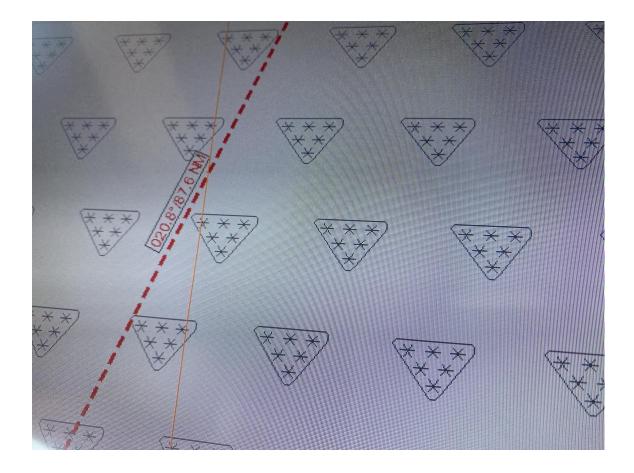
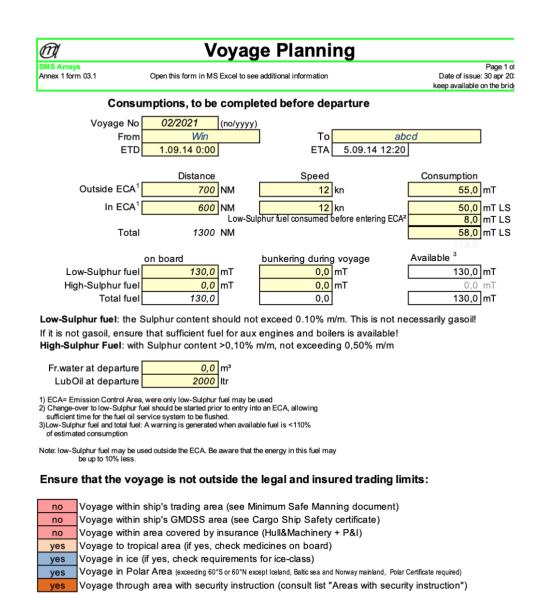


Figure 2. CATZOC on ECDIS screen.

### 4.6 Voyage Plan template

In our company, the following voyage plan template is used to streamline the voyage planning process and have it similar on every vessel in our company. This allows the bridge team to be manned on every vessel in the fleet and have them easily understand the planned voyage.

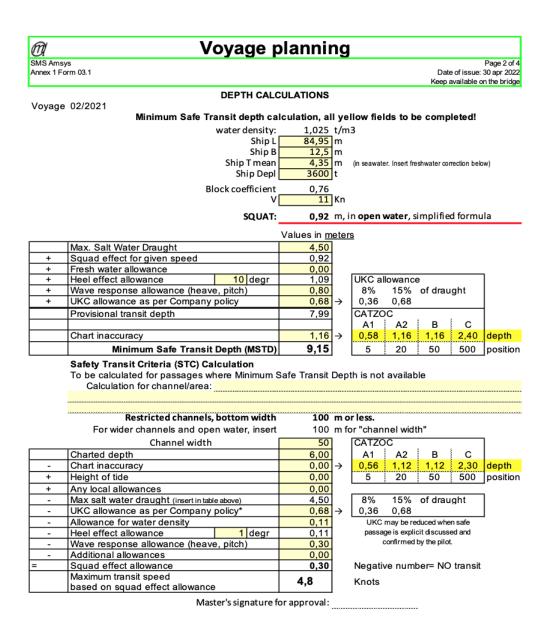
The following voyage planning template is from the Company's SMS.



Master's signature for approval

Figure 3. Voyage plan template page 1.

The first page of voyage plan shows the most basic information. This includes voyage number in the current year, from which port to what port the voyage takes place, is it a ballasted (B) or a loaded (L) voyage, the date and estimated time of departure, the distance of the voyage, estimated speed of the vessel during the voyage, estimated fuel consumption, how much fuel is available, how much fresh water is available, how much lube oil is available, is there bunkering during the voyage, is the voyage taking place in ice, is it in a polar area, is there any areas of security instructions and so on.



The second page of a voyage plan includes more detailed information about the voyage. In this page there are calculated two of the most important things about the voyage. These things are: Minimum Safe Transit Depth (MSTD) and Maximum transit speed based on squad effect allowance. MSTD shows our minimum allowed depth. This is calculated by taking into account different allowances and particulars. The allowances and particulars taking into account are: the ship's maximum saltwater draught, which is given to the 2nd officer by the chief officer, squad effect for given speed, which is calculated with simplified formula in the first part of this page, fresh water allowance, heel effect allowance, wave response allowance, which is draught increase due to heave and pitch movement of a vessel and comes from taking into account the weather forecast of the upcoming voyage, and under keel clearance (UKC) allowance, which comes from company's policy and takes into account the most inaccurate part of the chart used during the voyage.

On this page is also calculated Maximum transit speed based on squad effect allowance. This is done if the voyage goes through a narrow channel, on our vessel this is considered channel with a width of 108.8 meters or less. In this calculation, the following things are taken into consideration: the narrowest and shallowest part of the voyage, the chart's inaccuracy in that position, height of tide, any local allowances, maximum salt water draught of the vessel, UKC as per company policy, allowance for water density, heel effect allowance, wave response allowance, any additional allowances taken from pilot book, and with these allowances the maximum transit speed is calculated for the narrowest part of the voyage.

The MSTD and the maximum transit speed based on squad effect allowance have to always be positive numbers, otherwise transit is not allowed.

			Che	cked rout	e in ECDIS	All licenses a	vailable			Last update	
			ADP areas		e in Lobio.	All licenses a	valiable.				
										Last update	
			e-NP(pilots) nr	<u> </u>						Last update	
			Dep. Draught		m fwd		m aft			Stability, G'M	
			Air draught		m above v	waterline					
			Tidal info:								
15	52/30	100 100 100 100 100 100 100 100 100 100	137	Voyage	02/2021	from:	Win		to:	abcd	
-		<u>~</u>	Start setting	s:							
			ECDIS route: Safety Dept	7	port ABC to C	~~~~~	unt the equat t		abort income	acy, vessel's rolling	
			Safety Contour		m	Take mo acco	a second s		water density		
			Ahead, warning see		2 min.				rator density		
-			PS/SB, warning sec	**************	0,1 NM						
	x		Navtex stations		A, D						
	x		Satcom Navarea		1						
	x		Fuel change over		not in this voy	/age	If yes, attach				
		x	Ballast exchange		Yes		. If yes, attach	a pla	nning for ball	ast exchange.	
			Reporting points,	changes	in ECDIS sett	tings, speed lin	nits, any oth	ner re	strictions,	essential	
			navigational deta	ils, narrow	and shallow	passages etc	. Use attacl	hmen	nts as relev	ant.	
			1								Channel
			Report:	Port con	trol 10 min b	pefore departu	re				14
			Report:	Port con	trol, upon le	aving the fain	way				14
			ECDIS:	Set Safe	tv dept/safe	ety contour on	10 m after	leav	ing fairway	, and:	
			ECDIS:			ad to 6 min, P			····¥	·	
••••			Report		standby or						3
		~~~~~	Kepurc					1	- la stad		J
	x			upon en		Navtex statio					
		<u>X</u>	Ballast exchange			anned when >		norv	vegian coa	st	
			Warning			hours before	arrival				
			Pilot	call 3 ho	urs before p	ilot station					10
			Pilot	call 1 ho	ur before pil	ot station				ļ	10
			ECDIS:	before pi	lot boarding	: Safety Dept	6 m, Safety	Cor	ntour 7, an	d;	
				Warning	Sector ahea	ad to 3 min, P	S/SB to 0.1	NM			
-			Call Master		before pilot						
		******	Pilot			hout pilot and	master on	the l	hridae		
			T HOL					******			
						for inbound de	******	<i>alche</i>	eu)		
			Warning			re bridge, prep					
			Warning	Speed m	ax 5 kn bef	ore entering h	arbour				
1											
		~~~~~						•••••			
		****		~~~~~~				~~~~~~			
		~~~~~									
										ò	
										Î	

Master's signature for approval

Figure 5. Voyage plan template page 3.

The third page of the voyage plan template includes on the upper part of the page: the checklist for route available with latest updates to the charts used in ECDIS, the areas of Admiralty Digital Publications (ADP), the Admiralty Electronic Nautical Publication (e-NP) pilotage areas, the latest updates to these publications, departure draughts from forward and aft, the air draught, tidal information, and stability (metacentric height GM) information from chief officer.

The second part of this page includes ECDIS route name, ECDIS safety settings, Navtex station areas, Satcom Navareas, if there's any fuel change or ballasting during the voyage, and where it takes place, and information about upcoming reporting points, any information about fuel change, ballasting, any points where calling the master is necessary, pilotage, any warnings and call-aheads to ports with VHF channel numbers.

Ħ	Voyage Planning	
MS Amsys	nth	Page 4 c
nnex 1 form 0		sue: 30 apr 20
		able on the brid
	ster should check and approve each page of the voyage planning.	
Changes	s in voyage planning should not be used without master's approval.	
	er making the voyage planning and the master should be aware of vage Plan Guidance".	
Voyage	02/2021	
From	n Win To abcd	
ETD	D 1.09.14 0:00	
	Verified all checks for legal and insurance area limits Minimum Safe Transit Depth calculation verified Safe Transit Criteria calculated for relevant passages Last update of charts and publication acceptable ECDIS Route monitored Embarking and disembarking of pilot at departure Height restriction (bridges, overhead cables, etc.) properly recorded Reporting points properly recorded Are ECDIS settings changed at logical positions Recorded when master (or other specific person) must be on bridge Details of fuel changeover correct Details of Ballast Exchange correct	
	Narrow and shallow passages sufficiently described	
	Readiness of bowthruster recorded	
	Embarking and disembarking of pilot at arrival	
Notes:	Arrival conditions known: availability of suitable berth, any limitations and dangers.	
votes.		

Master's signature for approval

The fourth page of the voyage plan template is a checklist for the master to go through before the voyage. This page includes: the voyage number, date, from which port to where, estimated time of departure, and things master should check from the voyage plan.

# 5 Voyage from Halmstad to Wismar

#### 5.1 Introduction

In this chapter, the author describes his process of making an voyage plan for a voyage that took place in August of 2022.

The author got a notification of a upcoming voyage from Halmstad, Sweden to Wismar, Germany.

#### 5.2 Initial voyage plan.

When a voyage is confirmed, the first thing the author does is to check the routes he has already saved on the ship's ECDIS. Some of the ports the ship visits frequently and the appropriate route could be already saved in the ECDIS. If the route is there, he checks the berths the vessel is assigned in the ports and check, if his routes are from and to the correct berths. Minor adjustments may be needed. If the route is not available, the author starts by making an initial route. In this initial route, his aim is to get a general overview of the route to check that he has appropriate charts available. If he has any charts missing, he uses the Datema Chartplanner system to order appropriate charts and installs them to the ship's ECDIS.

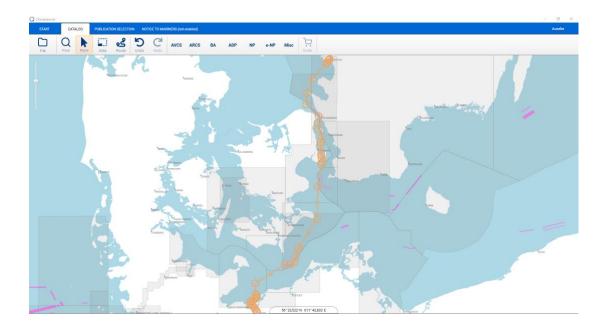


Figure 7. Checking the route for appropriate charts in the Datema Chartplanner system.

After making an initial route in the ECDIS, the author can export the route and import it to the Datema Chartplanner system, and check, if he has all the necessary charts for the voyage. If there are any charts missing, he can order them.

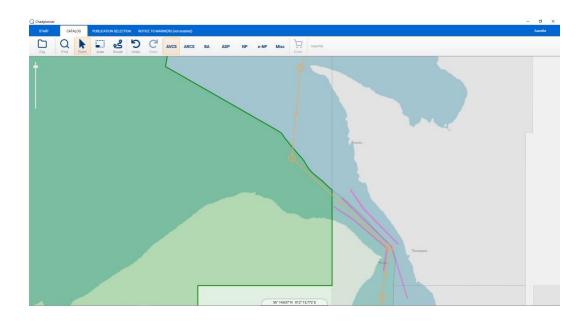
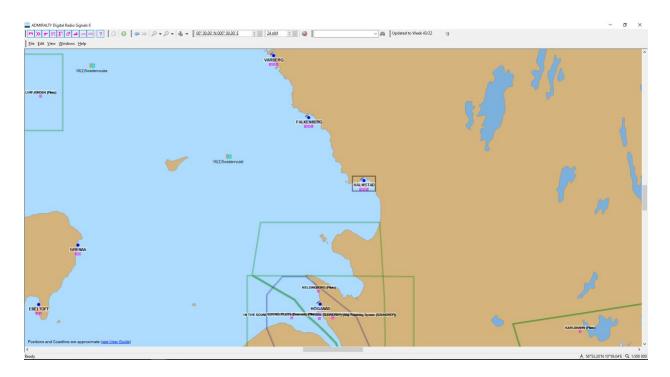


Figure 8. Missing chart on the route.

In figure 8, the route goes through a chart area that the author currently does not have. This can be seen as the missing chart is green. He purchases the missing chart and installs it in the ECDIS.

# 5.3 Detailed voyage plan

When the author has installed the missing charts to the ship's ECDIS, he starts producing a more detailed voyage plan. He starts by reading the port's pilotage requirements. The "Admiralty Digital Radio Signals 6" program is used for that. This program combines the most important information about the ports to an easy-to-read format.



# Figure 9. Admiralty Digital Radio Signals 6.

From this program, one can select ports and areas of interest and read the most important pilotage information about the area.

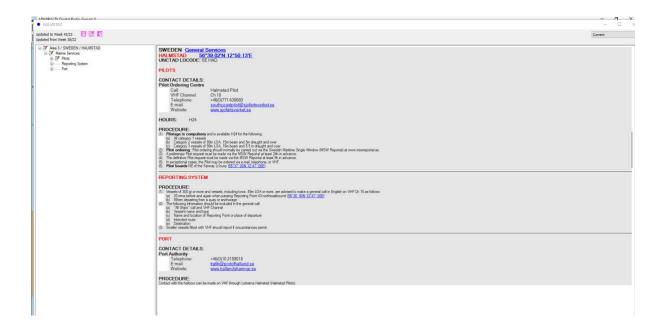


Figure 10. Admiralty Digital Radio Signals 6, information about Halmstad.

In this picture one can read the most important information about port of Halmstad. As our ship is a "Category 3" vessel in Sweden, meaning, we are a general cargo vessel of under 90 meters in length and under 16-meter beam, we do not require a pilot assistance when entering and leaving Halmstad. But for Wismar, as we are over 13 meters in beam, we require a pilot assistance.

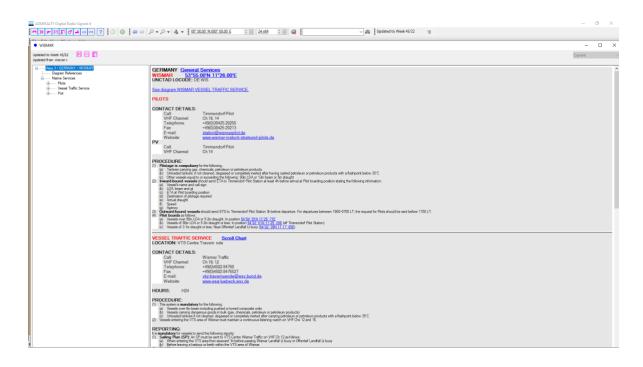


Figure 11. Admiralty Digital Radio Signals 6, information about Wismar.

The author then proceeds to write the information about pilotage and instructions of ordering them on a separate paper and gives it to the captain to make arrangements. After that, the author will start by going from one port to another, following the route on the ECDIS screen, adding waypoints, which include reporting points, pilot boarding points and other points of importance, to the route. When the author has marked a waypoint into the route, he will add it also to the voyage plan's Microsoft Excel file.

When the author has completed the waypoint section of the voyage plan, he will check the CATZOCs on the route. This is one of the most important parts, as we don't want our vessel to run aground, and having sufficient depth and calculating the minimum safe transit depth is of utmost importance. For this task, the author enables the CATZOCs in the ECDIS ENC. He goes over the route again, marking the narrowest and shallowest parts. In the Company's Voyage Plan guidance, confined waters are defined as waters, where the waterway has a width less than 8 times the vessels breadth, meaning for our vessel, it's 108,8 m or less in breadth. If our passage doesn't include a restricted channel, 108,8 is used in "channel width" cell instead. Furthermore, the Company Policy dictates, that the UKC margin must be at least 8% of the deepest draught in confined/shallow waters and 15% in open waters.

Then, the author checks in which Navtex station areas, ADP areas, e-NP areas, Satcom areas the passage takes place and enter the safety depth, safety contour, ahead waning sector, Port Side/Starboard Side warning sectors to the file. Before the voyage, all of these publications are updated.

If the vessel would have fuel change over or ballast exchange during the voyage, the calculation would be attached for the start/stop time and planning for ballast exchange. When the author has prepared all the necessary information to the Voyage Plan file, he has the master check the route and voyage plan the author produced. Then the author will get the stability calculation from the chief officer. From the stability calculation, the author inserts the ship's draughts, displacement, metacentric height (GM) and can calculate the air draught.

# 6 Pre-departure briefing

Before departure, the bridge team will have a briefing of the voyage ahead and the master double-checks the route and voyage plan and the stability calculation produced by the chief officer. The pre-departure briefing is an important part for the success of the upcoming voyage. With the pre-departure briefing we ensure that every member of the bridge team understands the plan for the upcoming voyage.

# 7 Departure

After the departure, the voyage plan is usually followed to the letter. If any deviations are necessary, the route changes must be approved by the master unless the changes are made to avoid danger, collision or are made to follow COLREG.

# 8 Overlook of the produced voyage

#### 8.1.1 General overlook of the produced voyage

The voyage started in Halmstad, Sweden, went through the strait of Øresund, heading west to Kadetrenden Traffic Separation Scheme and to the Bay of Wismar.

### 8.1.2 Produced route in ECDIS

The following image is the final route plan on the ECDIS screen, which was monitored during the voyage from Halmstad, Sweden to Wismar, Germany.

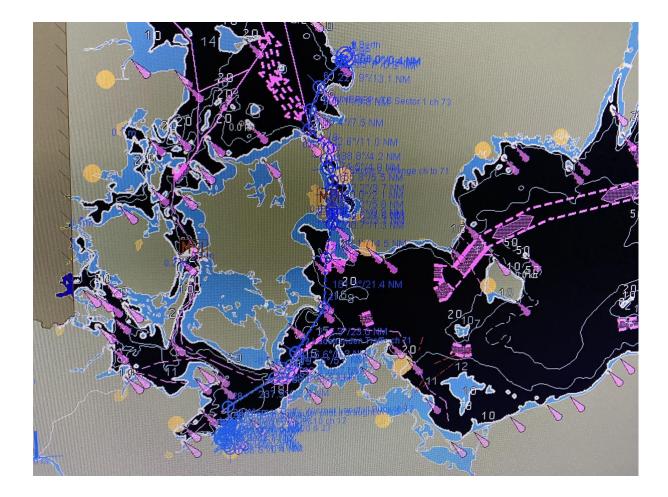


Figure 12. Produced route on ECDIS screen.

# 8.1.3 Produced voyage plan

The following images are the final voyage plan with the stability calculation, which was used during the monitoring of passage from Halmstad, Sweden to Wismar, Germany. This consists of a voyage plan file produced in Microsoft Excel with final stability calculations in conjunction with waypoints in the ECDIS.

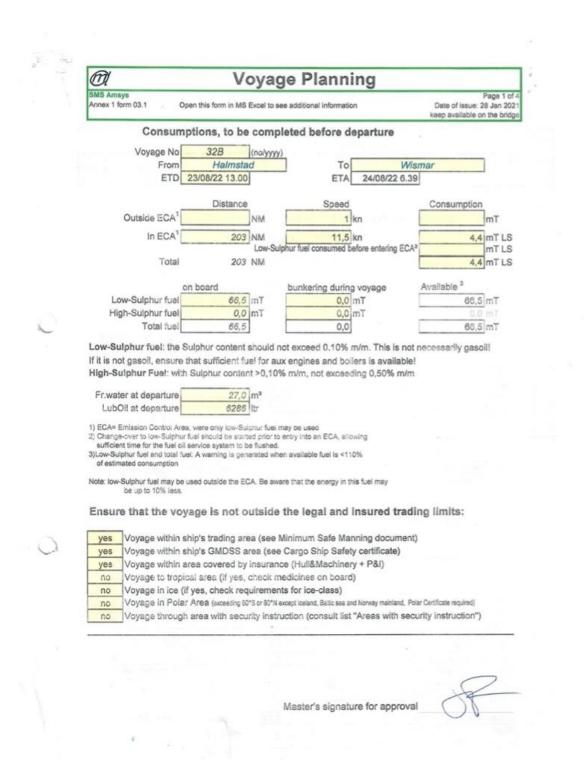


Figure 13. Voyage plan file page 1.

This is the first page of the produced voyage plan. This includes the voyage number, which is 32B, meaning this was the 32<sup>nd</sup> ballasted voyage in that year, the ETD, which was 23. August 2022, the ship departed at 1300, the voyage was 203 nautical miles long, the

estimated speed for this voyage was 11.5 knots, and estimated fuel consumption was 4,4 metric tons. There was no bunkering during the voyage.

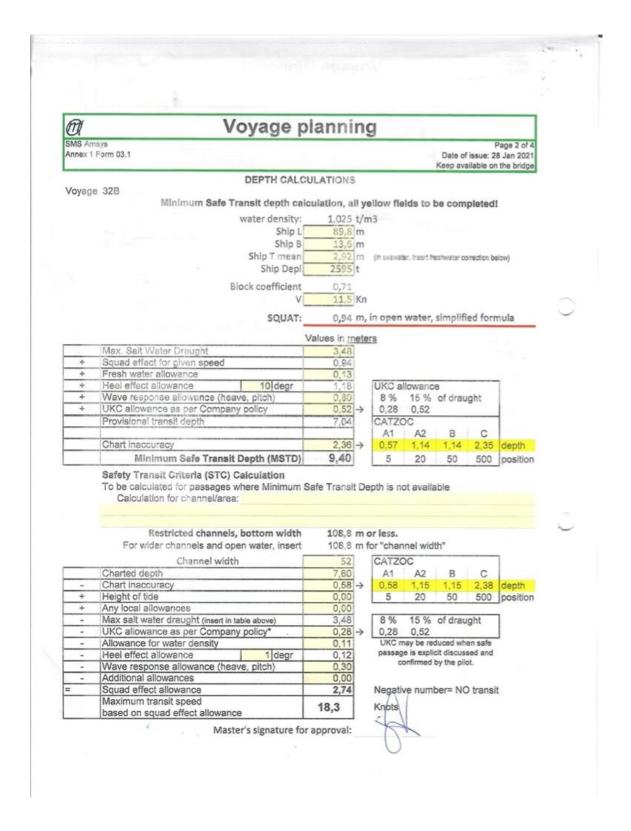


Figure 14. Voyage plan file page 2.

This is the second page of the produced voyage plan.

The ship's mean seawater draught was 2,92 meters, the displacement was 2595 tons, the block coefficient came out to be 0,71. The maximum salt water draught was 3,48 meters, squad effect came out to be 0,94, fresh water allowance 0,13, heel effect allowance 1,18, wave response allowance 0,8, the chart's inaccuracy in the most inaccurate position was C, so the UKC allowance came out to be 0,52. All of these allowances gave us the minimum safe transit depth of 9,40 meters.

For the maximum transit speed based on squad effect allowance, the narrowest part of the voyage was 52 meters with a depth of a 7,6 meters and chart inaccuracy of CATZOC A1, which gave us an allowance of 0,58. There was no tide or any local allowances to add.

The UKC came out to be 0,28, as it's 8% of the maximum sea water draught. The allowance taken off from water density was 0,11, the heel effect allowance was 0,12, the wave response was 0,3 and there were no additional allowances taken off. This gave us a squad effect allowance of 2,74 which gave us maximum transit speed of 18,3 knots.

2	DI IS An	LEVE .			Voya	ge Pla	nnin	g		Page 3 of 4
		form 0	0.1 Open this form in MS Excel to see additional information Date of issue keep available							
				ecked rou	te in ECDIS	. All licenses	available.	7	Last update	33
			ADP areas			3			Last update	35
			e-NP(pilots) nr			e-NP 18	1		Last update	33
			Dep. Draught	the second second second	m fwd	the second se	m aft		Stability, G'M	2,21
			Air draught	30,80	m above v	waterline				
		1.0	Tidal info:	Valena	900		Lie les als d		14.6	
	10	Ser is	///	Voyage	JED	trom	; Halmstad	to:	Wismar	
1	SI.	1.3	Calland							
			Start setting	IS:						
			ECDIS route:		Halmstad - V	Vismar				
×			Safety Dept		m	Take into acc			accuracy, vessel's	
××			Safety Contour	10			rolling and p	itching, water der	nsity	
×		1.1	Ahead, warning se PS/SB, warning se		12min 0.1 NM					
-	x		Navtex stations	retoi	I, J					
	х		Satcom Navarea		1					
1.1		x	Fuel change over		not in this vo			h calculation for		
		×	Ballast exchange	Allsst exchange not in this voyage If yes, attach a planning for b aporting points, changes in ECDIS settings, speed limits, any other restriction						
			navigational deta	ils, narro	w and shallo	w passages e	tc. Use atta	chments as rele	evant.	
							-			Channel
-	-			General			Departure			16
-	-				REP VTS			sector 1, N rep	line	73
					REP VTS			change ch to		71
-	-				den Traffic		No rep, lis			71
					torf Pilot	ETA at leas		arrival at PBP		14
-				Wismar	Traffic			ore Wismar Lt		12
-	-			John		at Wismar L		У		Cbn 11
-	_			Wismar			Ent area			12
-	-					25'-25E (off T				14
-				Wismar		Passing but				12
		-		Wismar		Passing but		23		12
				Wismar			Arrival			12
				Wismar I	Port		Working c	hannel		11
-										
			1							
121										
									*	
14										
-									1	



This is the third page of the produced voyage plan. We can see, that all of the ECDIS chart licenses are available and updated to week 33, the ADP area was 3, updated on week 33, the pilotage area was e-NP 18, updated on week 35, departure draught in the forward was 2,48 meters, aft at 3,60 meters. The GM was 2,21 meters, air draught 30,80 meters.

The route in ECDIS was called Halmstad – Wismar. Safety settings in the ECDIS were made as per company policy: safety depth at 10 meters, safety contour at 10 meters, ahead warning sector at 12 minutes, port side/starboard side warning sectors at 0,1 nautical miles.

The voyage goes through Navtex station areas I and J, Satcom area I.

There was no fuel change over or any ballast exchange during the voyage.

On this page there are also marked all the reporting points, pilot confirmation points, master calling points, and destination port control's VHF channel.

- M	Voyage Planning
SMS Amsys	Page 4 of 4
Annex 1 form 0	3.1 Date of issue: 28 Jan 2021 keep available on the bridge
-The mas	ter should check and approve each page of the voyage planning.
Changes	in voyage planning should not be used without master's approval.
	er making the voyage planning and the master should be aware of age Plan Guidance".
Voyage	32B
From	Halmstad To Wismar 23/08/22 13.00
The followin	g checkiist should be used by the master as a guidance, when checking the voyage plan:
	Checked consumption figures and fuel on board
	Verified all checks for legal and insurance area limits
	Minimum Safe Transit Depth calculation verified
	Safe Transit Criteria calculated for relevant passages Last update of charts and publication acceptable
	ECDIS Route monitored
	Embarking and disembarking of pilot at departure
	Height restriction (bridges, overhead cables, etc.) properly recorded
	Reporting points properly recorded
	Are ECDIS settings changed at logical positions
	Recorded when master (or other specific person) must be on bridge
	Details of fuel changeover correct
	Details of Ballast Exchange correct
	Narrow and shallow passages sufficiently described Readiness of bowthruster recorded
	Embarking and disembarking of pilot at arrival
Notes:	Linderving and discribining of processing
	Master's signature for approval
	N Real
	3

Figure 16. Voyage plan file page 5.

This is the final page of produced voyage plan. The master's checklist page.

Licensed to HMC		Schouwen	bank Nb 338		23 August 2022 12 Pag
		61	in Data		1
Name	: m/v Aurelie	Sh	ip Data	1008	· .
Remark	:			1998	
	Rederi Ab N	thalic			
Notes					
and the second sec					
The second second second second					
Name		Voy	age Data		
Remark	Ballast				
From Port	Halmstad			200000	
To Port	: Wismar			Date :	
Notes				Date :	
		Hydro	static Data		
Draught Data		Stabi	ility Data	Stren	gth Data
Trim		KMt	the second s	Max Shear Force	N
Draught Forward		KG-solid		Max Bending mom	N
Draught Midships Draught Aft		GM-solid		Max Torsion mom	N
And approved the second s	the second s	F.S. Corr.	0.03		llaneous
Max. Permissable Draught	and the second se	GM-fluid	2.21	VCG	4.
Free' 1		GM-req	0.25	TCG	-0
Air Dmught		GM-Margin	1.96	LCG	42.
LCB		GM-req.	Limit Curve	Act Disp	259
LCF		Country code		Sea Water Density	1.0
Heeling Angle	-0.35 d	Roll Period	6.71 s		
Distant			For Even Keel Draughts)		
Displacement Deadweight			t Sea Water Density		1.00
Available DWT To L.L.			t Draught Midships		2.9
		2741	t Load Line		Summer (
D-11		Loading	Summary		
Ballast Tanks Fresh Water	1119.22 t	<b>6</b> 1.4		Grain	0.00
The second secon	28.00 t	SindBe	1.50 t		0.00
Diesel Oil	67.50 t			liens .	N
Lub Oil		Cargo Spaces		RoRo Containers	N/ 0.00
Total : 1268.72 t		an alterna	40.121	A REAL PROPERTY OF	0.00
Weight : 1326.61 LCG : 37.500 T	CG: 0.000 VCG:		šhip Data		
Starboard is ( - )		and a second s	nd Origins		
feel To Starboard is ( - )		X Pos Of Cargo Item Is To C			
frim By The Bow( - )		Y Pos Of Cargo Item Is To C Z Pos Of Cargo Item Is To C			
forward Of APP Is (+)		All Vertical Limits Are Chec			
Above Base Is ( + )		All Transverse Limits Are Cl			
Note: All Units Are Metric					
SM in Ton*Metres					
		Contribute	C		
All requirement passed.		Condition Requi	rements Summary		and the second second second
in requirement passed.					

Figure 17. Stability calculation page 1.

This is the first page of a stability calculation produced by the chief officer. This accompanies the voyage plan produced by the author. From this page, the author gets information about displacement and stability (GM-fluid).

Licensed to HMC Sch	nouwenbank N	b 338					23 Au	zgust 202	2 12.5 Page
Ballast Tanks									
Forepeak WB CL		Weight		Fill %	Density	LCG	TCG	VCG	FSM
Deeptank WB CL		0.0			1.000	0.00	0.00	0.00	0
DB centretank 1WB CL		0.0	210 277		1.000	0.00	0.00	0.00	0
DB sidetank 1 WB SB		144.5			10 C C C C C		0.00	0.56	0.
		164.4;	20 0.2			63.71	-5.67	3.07	0
DB sidetank I WB PS		164.4	2 7.2	100	1.000	63.71	5.67	3.07	0
DB tank 2 C WB CL		0.0	0.0	0	1.000	0.00	0.00	0.00	0
Db tank 4 C WB CL		117.6	1 1.1	100	1.011	22.56	0.00	0.55	0
DB sidetank 2 WB SB		264.13		100	1.011	45.50	-5.71	2.95	0
DB sidetank 2 WB PS DB tank 3 WB SB		264.12	2 7.2	100	1.011	45.50	5.71	2.95	0
		0.0	0.0	0 0	1.011	0.00	0.00	0.00	0.
DB tank 3 WB PS		0.00	0.0	0 0	1.011	0.00	0.00	0.00	0
Fotal		1119.22	2			51.24	0.00	2.42	0
Diesel Tanks		Weight	Sounding	1020 44	Dessity	LCG	TCG	VCG	FEM
DB tank 3 C MDO CL			a designed which which have						FSM
Sidetank 3 MDO SB		0.00		a 105		0.00	0.00	0.00	0.
idetank 3 MDO PS		0.00		3 10		0.00	0.00	0.00	0.
Sidetank 4 MDO SB		0.00		5 0.00		0.00	0.00	0.00	0.
idetank 4 MDO PS		18.00	- E13	4 100		20.05	-5.91	2.05	3
ettlingt MDO DO SB		18.00				20.05	5.91	2.05	3
Paytank MDO DO SB		9.50			0.850	7.18	-4.21	5.13	5
iunker GO PS		6.00				6.36	-5.47	7.62	1.
		15.00			0.850	8.56	4.23	4.66	9
		1.00	1.0	52	0.850	4.23	-5.18	7.35	0.
0får~-		67.50				14.23	-0.22	3.64	22
irty Water Tanks		Weight	Sounding	Fill %	Density	LCG	TCG	VCG	FSM
ewage tank SL SB		0.00	where the second second second			0.00	0.00	0.00	0.0
otal		0.00			1.000	0.00	0.00	0.00	0.0
and Wester The Ac									
resh Water Tanks flerpeak FW SB		Weight	Sounding			LCG	TCG	VCG	FSM
fterpeak FW PS		14.00			1.000	2.41	-1.34	4.76	25.9
otal		14.00 28.00		45	1.000	2.41	1.34	4.76	25.5
		28.00				2.41	0.00	4.76	51.7
ub Oil Tanks		Weight	Sounding	Fill %	Density	LCG	TCG	VCG	FSM
irculation t LO CL		2.30	0.6	88	0.900	10.75	0.00	0.92	0.4
ub oil storage LO		4.08	2.0	49	0.900	10.01	-4.16	4.10	2.9
ub oiltank 2 SB		0.00	0.0	0	0.900	0.00	0.00	0.00	0.0
ub oiltank 3 SB		0.00	0.0	0	0.900	0.00	0.00	0.00	0.0
otal		6.38				10.28	-2.66	2.96	3.3
lud unks		Weight	Sounding	E31 64	Durrity	100	TCC	VCG	FSM
iny on SL		0.00	Sounding 0.0	0	1.000	LCG 0.00	TCG 0.00	0.00	0.0
udge tank SL		1.50	0.5	26	1.000	11.18	-1.87	0.28	1.2
otal		1.50				11.18	-1.87	0.28	1.2
ontainer Bay	. Weight	-	LCG	1	T	CG	-	VCC	1
ny 01(Hold)	0.00		0.00			00		0.00	
y 03(Hold)									
ay 04(Hold)	0.00		0.00			00		0.00	
av 05(Hold)	0.00								
ay 07(Hold)	0.00		0.00			00		0.00	
y 08(Hold)						00		0.00	
y O9(Hold)	0.00		0.00			00		0.00	
y U(Hold)	0.00		0.00			00		0.00	
y 12(Hold)	0.00		0.00			00		0.00	
y 13(Hold)	0.00					00		0.00	
iy 15(Hold)	0.00					00	0.00		
iy 15(Hold) iy 16(Hold)		0.00			00		0.00		
		0.00			00	- 1	0.00		
· · · · · · · · · · · · · · · · · · ·		0.00		0.		1	0.00		
y Minou)	0.00		0.00		0.			0.00	
y 01(Deck)	0.00		0.00		0.			0.00	
y 02(Deck)	0.00		0.00	- 1	0.			0.00	
	0.00		0.00	1	0.	00		0.00	6
y 03(Deck)		0.00				0.00			
iy 05(Deck) iy 05(Deck) iy 06(Deck)	0.00		0.00		0.	00		0.00	

Figure 18. Stability calculation page 2.

This is the second page of the stability calculation produced by the chief officer. This page contains information about the tanks and their weight and stability coordinates. There is also information about cargo spaces.

Licensed to HMC		Schouwen	bank Nb 33	8			-	23 Augu	st 2022	
						_		_		Page
Container Bay(Continued)			Weight	LCG		тс	0	-	VCO	-
Bay 07(Deck)			0.00	0.00		0.0				
Bay 09(Deck)			0.00	0.00		0.0			0.00	
Bay 10(Deck)			0.00	0.00		0.0				
lay 11(Deck)			0.00	0.00		0.0			0.00	
ay 13(Deck)			0.00	0.00		0.0			0.00	
ay 14(Deck)			0.00	0.00		0.0			0.00	
ay 15(Deck)			0.00	0.00		0.0		0.00		
ay 17(Deck)	0.00		0.0			0.00				
ay 18(Deck)			0.00	0.00		0.0		1	0.00	
ay 19(Deck)			0.00	0.00		0.0			0.00	
otal			0.00	0.00		0.0	~	+	0.00	
								-		
argo Spaces					Weight	XPos	Length	LCG	TCG	VC
rew and stores					20.00	30.00	64.40	41.00	0.00	7.
rain bulkhead 1					13.06	17.80	0.50	17.80	0.00	6.
rain bulkhead 2					13.06	17.80	0.50	17.80	0.00	6.
old homogeneous					0.00	45.94	61.80	45.94	0.00	5
mber on deck layer 1					0.00	45.80	61.80	45.80	0.00	16.
mber on deck layer 2					0.00	45.80	61.80	45.80	0.00	11.
mber on deck layer 3 aft survey weight on					0.00	45.80	61.80	45.80	0.00	12
					0.00	20.00	40.00	20.00	0.00	0.0
aft survey weight fwd app					0.00	20.00	40.00	20.00	0.00	0.0
a vey weight aft app					0.00	20.00	40.00	20.00	0.00	0.0
tal					46.1			27.9	0.0	6
		Ctob Blan	GZ Curve)							
		Stability	GZ Curve)						_	
						G	M-fluid	1		
2.40 +							1			
						-				
					/					
144				1						
									-	1
1 m		//								
		//								1-
		-								
1										
. 1										
4						_			-	
		-							40	40.0
		Angle of He	eel (degrees)	**		5				
		Angle of He	eel (degrees)	p		544				
			eel (degrees) GZ Curve)	-		5				
Angle (*)	Sin (*)	Stability ( KN	GZ Curve) sin(*)	s==	•	5.0		GZ		
Angle (*) 0	Sin (*) 0.000	Stability ( KN : 0.0	GZ Curve) sin(*) 000			5×*		GZ -0.013	4	
Angle (*) 0 2	Sin (*) 0.000 0.035	Stability ( KN 0.0 0.2	GZ Curve) sin(*) 000 225		L.	Sin .				
Angle (*) 0 2 5	Sin (*) 0.000 0.035 0.087	Stability ( KN 0.2 0.2	GZ Curve) sin(*) 000 225 560	0.013		514		-0.013		
Angle (*) 0 2 5 10	Sin (*) 0.000 0.035 0.087 0.174	Stability ( KN 0.2 0.2	GZ Curve) sin(*) 000 225	0.013	-	5		-0.013		
Angle (*) 0 2 5 10 12	Sin (*) 0.000 0.035 0.087 0.174 0.208	Stability ( KN 0.0 0.2 0.5 1.1	GZ Curve) sin(*) 000 225 560	0.013 0.163 0.388		5.0		-0.013 0.062 0.171		
Angle (*) 0 2 5 10 12 15	Sin (*) 0.000 0.035 0.087 0.174 0.208 0.259	Stability ( KN 0.0 0.2 0.5 1.1 1.3	GZ Curve) sin(*) 000 225 560 139	0.013 0.163 0.388 0.760		5.0		-0.013 0.062 0.171 0.378		
Angle (*) 0 2 5 10 12 15 20	Sin (*) 0.000 0.035 0.087 0.174 0.208	Stability ( KN 0.0 0.5 1.1 1.3 1.7	GZ Curve) sin(*) 000 125 560 139 165	0.013 0.163 0.388 0.760 0.908		5.0		-0.013 0.062 0.171 0.378 0.457		
Angle (*) 0 2 5 10 12 15 20 30	Sin (*) 0.000 0.035 0.087 0.174 0.208 0.259	Stability (	GZ Curve) sin(*) 000 225 560 139 565 717	0.013 0.163 0.388 0.760 0.908 1.127 1.484		5.0		-0.013 0.062 0.171 0.378 0.457 0.591 0.845		
Angle (*) 0 2 5 10 12 15 20	Sin (*) 0.000 0.035 0.087 0.174 0.208 0.259 0.342	Stability ( KN 02 02 1.1 1.3 1.7 2.3 3.4	GZ Curve) sin(*) 000 225 560 139 165 717 129 159	0.013 0.163 0.388 0.760 0.908 1.127 1.484 2.163		5.0		-0.013 0.062 0.171 0.378 0.457 0.591 0.845 1.296		
Angle (*) 0 2 5 10 12 15 20 30	Sin (*) 0.000 0.035 0.087 0.174 0.208 0.259 0.342 0.500	Stability ( KN 0.0 0.1 1.1 1.3 1.3 1.3 1.3 1.3 1.3 1	GZ Curve) sin(*) 00 125 560 139 165 117 129	0.013 0.163 0.388 0.760 0.908 1.127 1.484		jan -		-0.013 0.062 0.171 0.378 0.457 0.591 0.845		

Figure 19. Stability calculation page 3.

This is a third page of the stability calculation produced by the chief officer. This page contains information about cargo spaces and stability curve.

yage N		Ship's Name:	FROM:		1	ro:			Master's Name:	
Route name: Halmstad - Wismar WAYPOINTS										
WPT	Name	Position	Leg	Total Distance	X PORT X STBD	Turn Radius	Draught	UKC	Masthead	Overhead Clearance
0	Berth	56° 39.635 N 012° 51.290 E	XXX.X XXX.X	XXX.X	XXX.X XXX.X	XXX.X	XXX.X	XXX.X	XXX.X	XXX.X
1		56° 39.296 N 012° 50.949 E	209.0° 0.38 NM	0.38 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
2		56° 39.163 N 012° 50.838 E	204.5° 0.10 NM	0.49 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
3		56° 39.061 N 012° 50.194 E	254.0° 0.38 NM	0.87 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
4		56° 37.576 N 012° 48.136 E	217.4° 1.90 NM	2.76 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
5	PBP	56° 37.018 N 012° 47.170 E	223.7° 0.78 NM	3.54 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
6		56° 27.262 N 012° 31.340 E	221.9° 13.11 NM	16.65 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
7	SOUNDREP VTS Sector 1 ch 73	56° 18.083 N 012° 25.282 E	200.1° 9.80 NM	26.45 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
8		56° 10.618 N 012° 24.010 E	185.4° 7.48 NM	33.93 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
9		56° 03.155 N 012° 38.532 E	132.6° 11.04 NM	44.97 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
10		55° 58.976 N 012° 37.375 E	188.8° 4.27 NM	49.24 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
11		55° 55.033 N 012° 38.053 E	174.5° 3.97 NM	53.20 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
12	Sector 2, change ch to 71	55° 50.003 N 012° 42.081 E	155.8° 5.51 NM	58.71 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
13		55° 46.413 N 012° 40.699 E	192.2° 3.70 NM	62.41 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
14		55° 44.324 N 012° 40.702 E	180.0° 2.10 NM	64.51 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
15		55° 38.551 N 012° 41.387 E	176.2° 5.79 NM	70.31 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
16		55° 37.699 N 012° 41.731 E	167.1° 0.88 NM	71.18 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
17		55° 36.143 N 012° 41.941 E	175.6° 1.57 NM	72.75 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
18		55° 33.044 N 012° 42.385 E	175.4° 3.09 NM	75.85 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
19		55° 31.818 N 012° 41.568 E	200.7° 1.32 NM	77.17 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
20		55° 17.563 N 012° 37.541 E	189.1° 14.47 NM	91.64 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
21		54° 56.231 N 012° 36.673 E	181.3° 21.36 NM	112.99 NM	0.10 NM 0.10 NM	0.10 NM	Undefined	Undefined	Undefined	Undefined
inted: 1	10/23/22 09:12:59	Prepared by nav. Offic		1	Checked by M	laster			1	Page

#### Figure 20. Waypoints in ECDIS.

This is a voyage plan made by the author in the ECDIS. This page contains information about waypoints, their coordinates, distances from the first waypoint, berth in Wismar, and ECDIS safety settings.

# 9 Discussion

This portfolio shows, how a logical and streamlined voyage planning template can help young officers produce voyage plans quickly. This is important, as usually on a small tonnage vessel, there isn't much time left for voyage planning as all hands on deck are usually needed. Whether it's for mooring, unmooring, cargo hold cleaning, loading, discharging, bulkhead moving, or ballasting operations, the crews on small tonnage vessels are small compared to bigger vessels, and every crew member must help out where needed. The author's vessel had a minimum crew of 7 people, including the author himself. The author spent approximately an hour from getting the confirmation about the voyage until the last steps before getting the pre-departure information from the chief officer. Furthermore, having an easy and logical voyage planning template helps young officers get the hang of producing voyages more quickly, as it's something that isn't taught at school that extensively, as every company's policy requires different things to be considered and marked by the officer in the voyage plan.

Additionally, if an officer responsible for voyage planning moves inside the company from one vessel to another, having a standardized voyage planning template helps them produce voyages quickly and safely without having to have a more extensive familiarization done before getting to work, as they are familiar with the voyage planning system.

As one of the disadvantages the author can see is that if the voyage plan procedure is not thoroughly explained to a new officer, they might not completely understand the importance of each step and check in the process. This might lead to accidents. With paper charts and pilotage books, producing a voyage plan takes a lot longer time, as one has to draw out every leg of the route, one sees the dangers on a map, and has to find pilotage information from books. But on modern vessels, producing a voyage doesn't take that long time, as one just clicks and goes on ECDIS and has all the information available with just few clicks on ECDIS and electronic Admiralty books. And with that, one might lose the feeling of danger, as ECDIS usually has different safety settings integrated that warn about shallow waters and other dangers to navigation. But if the ECDIS' configuration is wrong, one might not see the dangers. As this was the author's first officer position with voyage planning duties, the author saw the importance of a well thought out voyage plan template, and how it helps to get acclimatized quickly with a new company, vessel, and their procedures.

# 10 List of figures

Figure 1. Zones of confidence, their accuracy, and symbols on ECDIS screen	5
Figure 2. CATZOC on ECDIS screen	6
Figure 4. Voyage plan template page 1	7
Figure 5. Voyage plan template page 2	8
Figure 6. Voyage plan template page 31	.0
Figure 7. Voyage plan template page 41	.1
Figure 8. Checking the route for appropriate charts in the Datema Chartplanner system.1	.3
Figure 9. Missing chart on the route1	.3
Figure 10. Admiralty Digital Radio Signals 61	.4
Figure 11. Admiralty Digital Radio Signals 6, information about Halmstad1	.5
Figure 12. Admiralty Digital Radio Signals 6, information about Wismar	.5
Figure 13. Produced route on ECDIS screen1	.8
Figure 14. Voyage plan file page 11	.9
Figure 15. Voyage plan file page 22	0
Figure 16. Voyage plan file page 32	2

# **11 Sources**

Rederi Ab Nathalie Safety Management System. (22. August 2022).